

**PRODUCT FEATURES** 

• **Small but mighty:** Dramatically reduced size and weight allows Pathfinder to be installed on board the smallest vehicles.

technology, the Pathfinder DVL provides an array of

- Phased Array: Unique phased array transducer design delivers outstanding position accuracy at a reduced size, eliminates the need for speed of sound correction, and reduces drag on your vehicle.
- XRT (Extended Range Tracking): Our patented option delivers up to 60% increase in bottom tracking range.
- Health Monitor: Provides insight and alerts in near real-time of potential problems including transducer health, operating time, and leaks from potential damage.
- **Water tracking:** Extend your vehicle's range of operability by enabling navigation even when bottom is out of range.
- INS-ready: Real-time standard deviation and time of validity output for highly accurate coupling with an Inertial Navigation System (INS) further improves your resulting DVL aided INS position accuracy.
- **ADCP:** Acoustic Doppler Current Profiling (ADCP) option expands scientific and operational capabilities as needs arise.
- **Budget minded:** Priced for smaller budgets, without the need to compromise on performance.

advanced internal algorithms and features you'd typically expect to find only in higher-end solutions. With up to 500 m of bottom tracking, in up to 6000 m of water, the Pathfinder delivers a solid, value-priced solution for vehicles ranging from small inspection class ROVs to large diameter AUVs.

Pathfinder's **bottom-detection** algorithms and singleping bottom location accuracy are underpinned by the broadband processing techniques that Teledyne RDI is known for. Pathfinder provides **highly reliable** velocity data for navigation and position control, even over challenging terrain. It can also be upgraded with current profiling as different projects may require.

The Pathfinder DVL is available off-the-shelf in self-contained or OEM configurations, providing you with a footprint and flexibility that's just right for your unique vehicle requirements.



## Pathfinder Phased-Array DVL

## **TECHNICAL SPECIFICATIONS**



		600 kHz	300 kHz (OEM only)
Bottom Tracking	Maximum Altitude <sup>1</sup>	89 m (up to 150 m optional)	275 m (up to 500 m optional <sup>2</sup> )
	Minimum Altitude	0.15 m	0.3 m
	Velocity Range <sup>3</sup>	±1.6m/s (<0.35m altitude); ±9m/s (>0.35m altitude) No Tilt	±1.6m/s (<0.35m altitude); ±9m/s (>0.35m altitude) No Tilt
	Long Term Accuracy⁴	±0.06% ±0.1 cm/s (<4 m altitude); ±0.2% ±0.1 cm/s (>4 m altitude)	±0.08% ±0.1 cm/s (<8 m altitude) ±0.3% ±0.1 cm/s (>8 m altitude)
	Long Term Accuracy <sup>5,7</sup>	±1.15% ±0.1 cm/s	±1.15% ±0.1 cm/s
	Precision @ 1 m/s	±0.5 cm/s @ ½ alt.	±0.6 cm/s @ ½ alt.
	Resolution	0.01 mm/s	0.01 mm/s
	Maximum Ping Rate <sup>6</sup>	12 Hz	7 Hz
<b>Water Profiling</b>	Maximum Range <sup>1,2</sup>	47 m	150 m
	Minimum Range	1.9 m	4.5 m
	Velocity Range <sup>3</sup>	±15 m/s	±15 m/s
	Long Term Accuracy	±0.3% ±0.1 cm/s	±0.6% ±0.1 cm/s
Acoustic	Center Frequency	614.4 kHz	307.2 kHz
	Source Level (re 1 µPa)	215 dB@1 m	220 dB@1 m
	1-Way Beam Width	2.2°	2.7°
	Number of Beams	4-phased array	4-phased array
	Beam Angle (nominal)	30°	30°
	Bandwidth (nominal)	6.25% of center freq.	6.25% of center freq.
Environmental	Maximum Operating Depth	SC - 300 m, 500 m; OEM - 300 m, 1,000 m and 6,000 m	1,000 m
	Operating Temperature	-5°C to 45°C	-5°C to 45°C
	Storage Temperature	-30°C to 60°C	-30°C to 60°C
Internal Sensors	Leak Detection	Dual Up & Down in SC / One located in OEM Transducer	One located in OEM Transducer
	Health Monitor	Transducer Health, Operating Time	Transducer Health, Operating Time
Power	Average Power (@ 24 VDC)	2.6 W (3.4 W with Ethernet enabled)	13.5 W (14.4 W with Ethernet enabled)
	Quiescent Power	1.3 W (2.2 W with Ethernet enabled)	1.3 W (2.2 W with Ethernet enabled)
	Input Voltage (VDC)	10.7 - 36 VDC	12-36 VDC
	Surge Current	<4 A	<6.5 A
Communications	Ethernet & RS232 (or optional RS422 only installed at factory)		
Dimensions (in.)	Contact RDI for specific configuration W & D		

1. @5°C and 35 ppt, salinity, @ max V

 420 m in typical conditions, up to 500 m in ideal conditions
When mounted with beam @ 45°
4. ECCN 6A001 6. @ 5% of maximum altitude

7. Max speed =  $\pm 1.6$  m/s (<0.35 m altitude) &  $\pm 9$  m/s (>0.35 m altitude) No Tilt



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